

Hardware Instruction for HCA1P, HCA2P Series Programmable Controller

Manual No.	170100008A
Manual version	V1.1
Date	June.8th.2017

► 1 .Product overview

•1.1 Product naming rules

$$\frac{\text{HC}}{(1)} \quad \frac{\text{A2P}}{(2)} \quad \frac{-36X}{(3)} \quad \frac{24Y}{(4)} \quad \frac{\text{R(T)}}{(5)} \quad \frac{-\text{A}}{(6)}$$

Code	Contents
1	HC indicates the Chinese Character Pinyin Initials 'HeChuan
2	A2P indicates series number of PLC.
3	36X indicates 36 input points; Input points of A1P series: 8X, 12X, 16X Input points of A2P series: 14X, 24X, 36X
(4)	24Y indicates 24 output points; Output points of A1P series: 6Y、8Y、14Y Output points of A2P series: 10Y、16Y、24Y Total number of input& output points: A1P: 14 points, 20 points, 30 points A2P: 14 points, 24 points, 40 points, 60 points
5	R(T) indicates output type of PLC R: relay output T: transistor output
6	A(D) indicates power supply type of PLC A: AC 100V~240V input D: DC 20.4V~26.4V input

●1.2 Part names



2.Power specification

● 2.1AC power module Specification

lite and a		HCA1P		HCA2P									
Items	14 points	20points	30 points	24 points	40points	60 points							
Rated voltage	AC 100 - 24	AC 100 - 240V											
Rated frequency	50/60 Hz	50/60 Hz											
Allowable momentary power failure period		10ms,If less than 10 ms, the PLC will continue operation. If 10 ms or more, the PLC will be shut down											
Power fuse	3.15A			5A									
In-rush current		lax. 15A for 5 lax. 25A for 5			lax. 30A for 5 lax. 50A for 5								
Power consumption	19W	20W	21W	30W	32W	35W							
24V DC External	24V DC 500)mA (Not rele	vant to the co	onnection of e	expansion m	odule)							

Attention: Includes Input current (7mA or 5mA perpoint)

► 3 .Input / Output wiring diagram

•3.1 Input wiring diagram

Programmable controller(Sinking)



Programmable controller(Sourcing)



①Status indicator POWER LED: Lit when power is ON. RUN LED: Lit when executing a program ERROR LED: When program error, indicating lampflashes When CPU error, indicating lamp lit
②Input indicator: From X0 to X7 in the first row, from X10 to X17 in the second row.
③Output indicator: From Y0 to Y7 in the first row, from Y10 to Y17 in the second row.
④RS485 communication port: Operating according to arrow directions
⑤RS422 communication port: Operating according to arrow directions
⑥Reserved
⑦Terminal cover
⑧Right expansion cover
⑨Front cover
⑩Battery interface
⑪Run/Stop switch

1.3 External dimension

Points	L(mm)	W(mm)	H(mm)
HCA1P-8X6Y(14 points)	60.5	90	75
HCA1P-14X10Y(20 points)	75.5	90	75
HCA1P-20X14Y(30 points)		90	75
HCA2P-14X10Y(24 points)		90	82
HCA2P-24X16Y(40 points)		90	82
HCA2P-36X24Y(60 points)	175	90	82

1.4 Performance Specification

Items	Performance
Memory capacity	 Built-in 2K/8K EEPROM(A1P:2K,A2P:8K) 2K, including comments, file register Rewrite: 20,000 times
Install expansion unit/IO	Optional f or A2P
Transistor output modules	Optional
High-speed counter	 Increment: 60 kHz*2 counter, 10 kHz*4 counter Up/down: 60 kHz*1 counter, 10 kHz*1 counter Pulse plus direction: 100 kHz*2 counter Differential phases (4×): 50 kHz*1 counter, 5 kHz*1 counter
Pulse output	Support(Only with transistor output modules)
Rs422 communication port	Provided
Rs485 communication port	Provided
Corresponding links	 Simple PC links (8 base units(max.) can be connected) PC links(can be used as a sub-station connection) Parallel links(2 main unit can be linked)
Clock	Provided
Battery	Can be used(Sold separately)
Backup time of capacitor	7 days (at most), at 25 °C(More than 30 minutes after start-up)
Battery-free operation	If there are no batteries, we have to do no battery operation. If power outage more than 7 days, only EEPROM data can be kept.

• 3.2 Output wiring diagram

3.2.1 Relay output specification and wiring

Outpu	ut type		Relay					
External power sup	oply	≤ DC3 ≤ 240 if not	30V V(It should be lower than AC 250V consistent with CE/UL/CUL)					
Maximum load			The total load current should not exceed following values of common collector. Output 1 point common collector:2A Output 4 point common collector: 8A Output 8 point common collector: 8A					
	Inductive load	80VA						
Minimum	load	DC5V 2mA (Reference value)						
current	uit leakage	-						
Response	OFF→ON	Abou	t 10 ms					
Time		About 10 ms						
Circuitisc		Mechanical isolation						
Operation	indication	When	relay coil is energized, LED is lit.					



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\star Precaution:

Protection circuit for load short-circuit: A short-circuit at a load connected to an output terminal could cause burnout at the output element or the PCB. To prevent this, a protection fuse should be inserted at the output.

Contact protection circuit of inductive load: An internal protection circuit for the relays is not provided in the relay output circuit for this product. It is recommended to use inductive loads with built-in protection circuits. When using loads without built-in protection circuits, insertan external contact protection circuit composed of surge absorber to reduce electromagnetic

interference and extend the product life

• 3.2.2 Transistor output specification and wiring

1.Sinking output wiring

Externa	l Power supply	DC5~30V	
Maximum load	Resistive load	The total load current should not exceed the following values of common collector resistance load. Output 1 point common collector: 0.5A Output 4 point common collector: 0.8A Output 8point common collector: 1.6A	
	Inductive load	12W/DC 24V	
Minimum l	oad	-	
Open circu	iit leakage current	≤ 0.1 mA / DC30V	
ON Voltage	e	≤ 1.5V	

Fuse



• Attention: All outputs are set as sinking output modes in all HCA1P/HCA2P series with transistor output.

▶ 4.High-speed counter input/ pulse output instruction

[Input] high-speed counter function

1 phase: č0kHz * 2 points,10kHz *4 points 2 phase: 30kHz * 1 points, 5kHz X1 points [Input] Pulse latch function

To capture signal of 10μs(X0,X1) or 50μs(X2~X5)

[Input] external interrupt function

By external signals of 10µs(X000,X001) or 50µs(X002~X005),it can process interrupt program first.

[Output] pulse output function

2 pulse train outputs 100kHz (max.) at the same time(transistor output base units only). With special positioning instruction of ZRN, DRVI、DRVA.

● 4.1 High-speed counter input example

High-speed counter coil drive depends on Contact points. In high-speed counting, please use energized contact points. Example: M8000(monitoring) Input number corresponding to C235





When specifying counting number into relay, High-speed counter cannot count correctly

•Please note that if we use contact device of analog switch to count, switch vibration may cause counting error.

•If high-speed counter coil programmed, the corresponding input filter in input relay will automatically be $20\mu s$ (X000, X001) or $50\mu s$ (X002~X005) (initial value: 10 ms)

•Serial number of input relay cannot be used with same input instructions at the same time, e.g: Input interrupt processing(pointer), pulse output density instruction SPD

•Output contact points of high-speed counters will not execute instructions even with current value, unless counting input pulse set.

•When output coil of high-speed counter(OUT C***) on/off, it can start/ stop execution counting. Output coil should be programmed in the main program. If programmed in step ladder circuit, subroutine, interrupt handlers, Counting and Counting Stop Function can work until step ladder circuit and subroutine perform.

•4.2 High-speed counter output example (only applicable to transistor output)



ullet PLSY instruction: produces quantitative pulse with assigned frequency

S1: assigned frequency

HC1AP, HC2AP: 16-bit instruction \rightarrow 1~32, 767(HZ), 32-bit instruction \rightarrow 1~100, 000(HZ) When S1specified word device changes during instruction execution, output frequency changes accordingly.

S2: assigned pulse volume

●Allowable setting range: 16-bit instruction→1~32, 767(PLS), 32-bit instruction→1~2, 147, 483, 647 (PLS)

Setting value is zero, the generated pulse do no limit.

In DPLSY instruction, (D1, D0) can be set as pulse value.

During instruction execution , when S2 specified word device changes, it starts executing change instruction in next instruction drive.

D specifies Y serial number of output pulse, only valid with Y000 or Y001(Please use transistor output mode)

HCA2P-24X16Y□

E	S/S	X1 X	(3 X	5 X	7 X	11 X	(13 X	15 X	17 X	21 X	23 >	(25 X	27
1 L	۷ X	0 X2	X4	X6	X10	X12	X14	X16	X20	X22	X24	X26	
0V Y0 Y1 Y2 • Y4 Y6 • Y10 Y12 • Y14 Y16 •													
24V CO	M0 CO	M1 COM2	Y3	COM3	Y5	Y7	COM4	Y11	Y13	COM5	Y15	Y17	

HCA2P-36X24Y□

E	S/S X1	X3	X5 X7	X11 >	(13 X15	X17	X21	X23 🛛	X25 X2	27 X31	X33 X	X35 X37	X41 >	X43
L	N XO X	2 X4	X6	X10 X12	X14 X	(16 X2	20 X2	22 X24	4 X26	X30 X	32 X34	+ X36 X	40 X42	2
0V	Y0 Y1	Y2	• Y4	Y6	• Y10	Y12	•	Y14	Y16	Y20	Y22	• Y24	Y26	•
24V CC	MO COM1 CO	M2 Y3	COM3	Y5 Y7	COM4 Y	/11 Y1	3 CO	M5 Y15	5 Y17	COM6 Y	21 Y23	COM7 Y	25 Y27	'

Difference between DC power terminal type and AC power terminal type:

	AC p	owe	rsup	ply	_		DC p	ower	sup	ply
	E	Ξ	S	/S			E		S	/S
L	-	١	N			6	Ð	6	9	

•X000 is OFF, output interrupts. Reset NO, it starts from initial state. Continuous pulse occurs, X000 will be OFF, Y000 will be OFF, too.

• Duty ratio of pulse is 50% ON, 50% OFF. Output control is not affected by scan cycle, then interrupt processing.

• Pulse completing, marking the end of M8029 action

● 5.Terminal arrangements for HCA1P &HCA2P series

HCA1P-8X6Y□

	E	E S/		/S X		(1	1 X		Х	5	Х	7
L	_ N		1	Х	X0		2 X		4	Х	6	
	0	V Y		0 Y		1	Y	2	Y	4		
24	ίV	CO	M0	CO	M1	CO	M2	Y	3	Y	5	

HCA1P-12X8Y□

	E			′S	X1		Х							11	X	3
l	L N		Х	(0 X		2	X	X4		6	X	0	X	12		
	0	V	Y	0	Y	1	Y	2	Y	3	Y4 M4	4	Y	6		
24	4V	CO	M0	CO	M1	CO	M2	CO	M3	CO	M4	Y	5	Y	7	

HCA1P-16X14Y

	E	Ξ	S/																	15		17
l	Ĺ	1	1	S/	′S	Х	0	X	2	Х	4	Х	6	X	0	X1	12	X	4	X1	6	
	0	V	Y	0	Y	'1	Y	2	Y	4	CO	M3	Y	7	Ϋ́	11	Y1	2	Y	4		
24	4V	CO	M0	CO	M1	CO	M2	Y	3	Y	5	Y	6	Y1	0	CO	M4	Y1	3	Y1	5	

B

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HCA2P-14X10Y□

			S/S													
L	1	1	Х	0	Х	2	Х	4	X	5	X	10	X	12	X1	4
	0V / CO	Y(0	Y	1	Y	2	Y	3	Y	5	Y	6	Y1	0	٠
24	1 00		$\overline{\mathbf{CO}}$	M1		MO	co	M3	V	<i>'</i> .	[colored]	M/i		7	V	11

